

Simple / Super Simple

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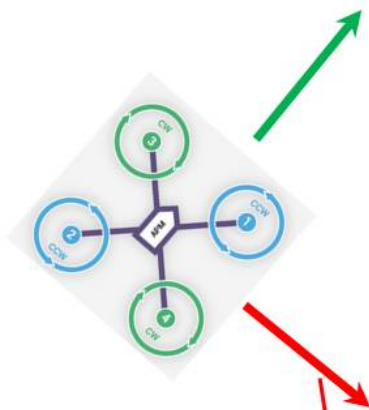
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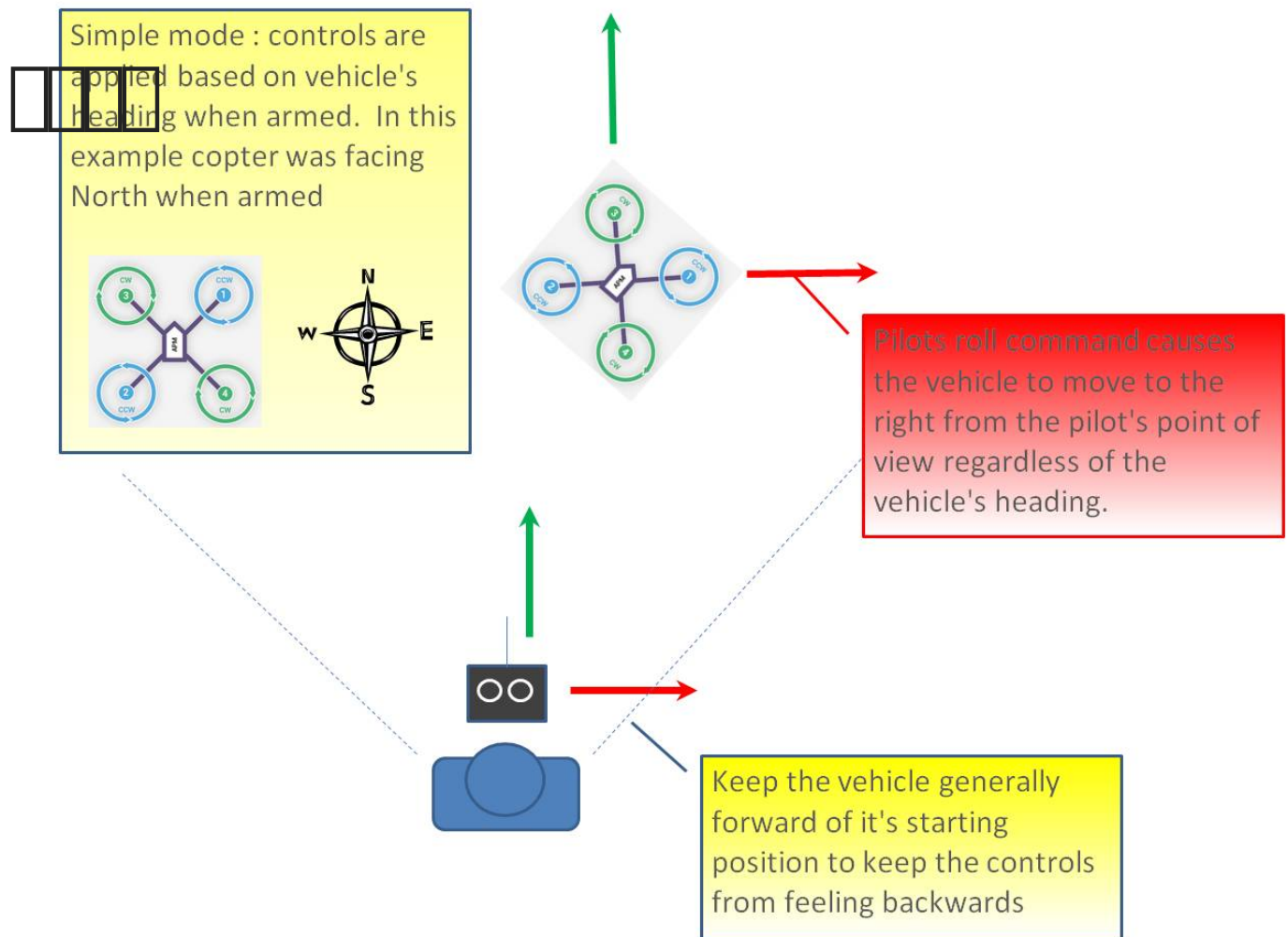
Normal controls apply
pilot input from the
vehicle's perspective



Pilots roll command causes the vehicle to roll to it's right.

1. The first parameter is the vehicle's heading in degrees. The second parameter is the vehicle's roll in degrees. The third parameter is the vehicle's pitch in degrees. The fourth parameter is the vehicle's yaw in degrees. The fifth parameter is the vehicle's roll rate in degrees per second. The sixth parameter is the vehicle's pitch rate in degrees per second. The seventh parameter is the vehicle's yaw rate in degrees per second. The eighth parameter is the vehicle's roll acceleration in degrees per second squared. The ninth parameter is the vehicle's pitch acceleration in degrees per second squared. The tenth parameter is the vehicle's yaw acceleration in degrees per second squared.

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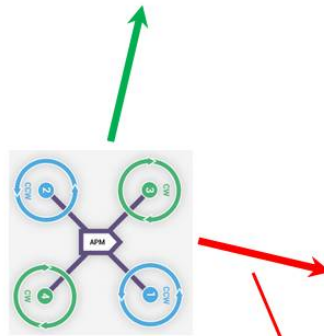


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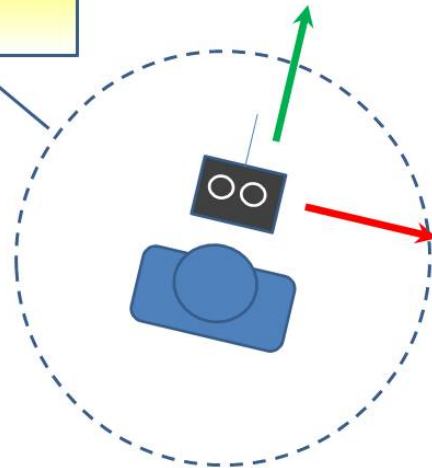
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Super Simple mode : controls are applied based on the vehicle's GPS position relative to home.



Pilot vs vehicle control angles are not updated within 10m of home



Pilots roll command causes the vehicle to move to the right from the pilot's point of view regardless of the vehicle's heading and even if the vehicle moves behind the pilot.

The vehicle's GPS position is used to calculate the distance from the home point. If the distance is less than 10m, the vehicle's heading is not updated. This is because the vehicle's heading is not updated within 10m of home. The vehicle's heading is only updated when the distance from home is greater than 10m. This is because the vehicle's heading is not updated within 10m of home. The vehicle's heading is only updated when the distance from home is greater than 10m. This is because the vehicle's heading is not updated within 10m of home. The vehicle's heading is only updated when the distance from home is greater than 10m.



