

PosHold

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, PosHold GPS ,** ** **

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-  ,  45° (  **ATC ANGLE MAX**
)   

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- Mission Planner 1.2.92.2 build 1.1.5117.35558
- COM15 115200 DISCONNECT
- Link Stats...
- 345 N 15 30 41E 60 75 E
- 100% 20:19:55
- DISARMED
- AS 0.1 GS 0.1
- Stabilize 0>0
- GPS: 3D Fix
- Quick Actions Gauges Status Servo Telemetry Logs DataFlash Logs Scripts
- Altitude (m) GroundSpeed (m/s)
- 0.44 0.06
- Gps HDOP 2.69
- Display This
- | | | | | | | | | | |
|---|---|-----------------------------------|---------------------------------|-------------------------------------|---|--|--|---------------------------------------|--------------------------------------|
| ☐ roll | ☐ altd1000 | ☐ ay | ☐ gyrosq | ☐ ch1out | ☐ nav_pitch | ☐ distTraveled | ☐ HomeAlt | ☐ accel_cal_y | ☐ remnoise |
| ☐ pitch | ☐ altd100 | ☐ az | ☐ rxrssi | ☐ ch2out | ☐ nav_bearing | ☐ timeInAir | ☐ DistToHome | ☐ accel_cal_z | ☐ localsnrdb |
| ☐ yaw | ☐ airspeed | ☐ ex | ☐ ch1in | ☐ ch3out | ☐ target_bearing | ☐ turnrate | ☐ ELToMAV | ☐ sonarrange | ☐ remotesnrb |
| ☐ groundcourse | ☐ targetairspeed | ☐ gy | ☐ ch2in | ☐ ch4out | ☐ wp_dist | ☐ radius | ☐ AZToMAV | ☐ sonarvoltage | ☐ DistRSSIRem |
| ☐ alt | ☐ asratio | ☐ gz | ☐ ch3in | ☐ ch5out | ☐ alt_error | ☐ targetaltd100 | ☐ press_abs | ☐ freemem | ☐ hwvoltage |
| ☐ altasl | ☐ groundspeed | ☐ mx | ☐ ch4in | ☐ ch6out | ☐ bar_error | ☐ targetalt | ☐ mag_declination | ☐ load | |
| ☐ altoffsethome | ☐ verticalspeed | ☐ my | ☐ ch5in | ☐ ch7out | ☐ aspd_error | ☐ battery_voltage | ☐ gyro_cal_x | ☐ brklevel | |
| ☐ epsstatus | ☐ wind_dir | ☐ mz | ☐ ch6in | ☐ ch8out | ☐ xtrack_error | ☐ battery_remain | ☐ gyro_cal_y | ☐ rssi | |
| ☒ gpshdop | ☐ wind_vel | ☐ magfield | ☐ ch7in | ☐ ch3percent | ☐ wpno | ☐ current | ☐ gyro_cal_z | ☐ remrssi | |
| ☐ satcount | ☐ ax | ☐ accelisq | ☐ ch8in | ☐ nav_roll | ☐ climbrate | ☐ battery_usedm | ☐ accel_cal_x | ☐ noise | |
- GEO 36.324346 138.639203 0.44 Tuning Auto Pan Zoom 18.7

- ArduPilot Copter · PosHold Mode · CC BY-SA 3.0

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□ Admin □□ 2026-10-09 14:39:00 UTC

□ Admin □□ 2026-10-10 01:45:32 UTC