



10个字节 (4个字节 GPS, 4个字节) 1个字节 , 10个字节 .
 4个字节 GPS 10个字节 , 4个字节 ** 4个字节 GPS 4个字节 ** 4个字节

2个字节

- 4个字节 , 10个字节 4个字节
- GPS 4个字节 , 4个字节 (4个字节)



10个字节 4个字节 10个字节 4个字节 HDOP, 4个字节
 4个字节 10个字节 10个字节 4个字节 10个字节 ,
 4个字节 4个字节 , 4个字节 , 4个字节 1000个字节



** 4个字节 ** 4个字节 GPS, 4个字节 4个字节 , 4个字节 4个字节



** 4个字节 ** 10个字节 4个字节 10个字节 .
 10个字节 . 4个字节 10个字节 , 4个字节 , 4个字节 4个字节
 10个字节 4个字节



4个字节 **AltHold ** 4个字节 **sonar 4个字节 lidar** 4个字节 , 10个字节
 4个字节 , 4个字节 url= (4个字节). 10个字节



- Disable the GPS by setting **GPS1_TYPE** to 0
- Configure the ****battery failsafe**** to "Land" by setting ****BATT_FS_LOW_ACT**** = 1
- Configure the ****radio failsafe**** to "Enabled always Land" by setting ****FS_THR_ENABLE**** = 3
- Disable the ****fence**** by setting ****FENCE_ENABLE**** = 0
- Use a downward facing sonar or lidar (if available)

Safe Indoor Flying Don'ts

- Don't fly in small confined spaces. Use common sense, flying inside a warehouse with a high roof = OK, bedroom = not OK.
- Don't use Auto* modes

* Autonomous and semi-autonomous modes require a position estimate. This can come from GPS or from ****Non-GPS Navigation**** sources such as optical flow, external navigation, or motion capture systems. In ArduPilot 4.7 and later, the EKF origin can be automatically saved and restored across power cycles — see ****Persistent Origin Storage**** for details.

**** Non-autonomous modes include ****Stabilize**** and ****AltHold******



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 Admin  2026-10-09 14:41:57 UTC

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