



CH () / / , CH rover RC , .

[illegible]

“ `./ images/mp setup flight mode.png ( )` .

Motor. Mission Planner: Flight Mode Screen (Copter) (□□).

[/]

$$[\square\square\square\square = \square\square\square\square] \cdot \square : \cdot / \cdot / \cdot / \square\square / \square\square\square\square\square\square\square\square$$

“ ” : ./ / Config plane.png

$$\begin{array}{|c|c|c|c|c|c|c|} \hline & & & & & & \\ \hline \end{array} : \begin{array}{|c|c|c|c|c|c|c|} \hline & & & & & & \\ \hline \end{array} \quad \left(\begin{array}{|c|c|} \hline & \\ \hline \end{array} \right)$$

[/]

```
[mode = "rover"]. . : ././ / / FlightModesConfig Rover.png
```

“ ” : ./ / / Config Rover.png

 : (Flickr)

```
[/] [ ] ["",copter,rover,blimp"]. [ ] [ ] :
```

Specn un Swant

[illegible]

```
[/[] ] [[][][] = "copter"]. - (Copter) [][][][][][]
```



[/]

```
[0][1][2][3] = "copter". - (Copter)
```







```
[/\] ] [==== = "copter,rover,blimp"]. - [==== , [==== [==== [/\] ] [==== = "copter"
[ . (Copter) [==== ** (a.k.a.ch7,ch8[==== ). [ , [==== [==== RTL [ /
[ ] [==== ="sub" ]. [ **FLTMODE CH[==== 6 PWM[==== [==== GCS
[==== [==== [==== [/\] ]
```



dã [] [] [] [] [] [] ArduPilot [] [] [] [] [] [] [] [] [] []

```
[Copter] = "copter". Copter , ( ) 5 . [/] [
    = " ". **FLTMODE CH** 8 [/] [
    = "rover". 2019 1 1 , 2017 1 1 . Rover , ** MODE CH **
    8, [/ [ = " ". , **FLTMODE CH "0",
RC , RC [/
=====
```


 PWM ,

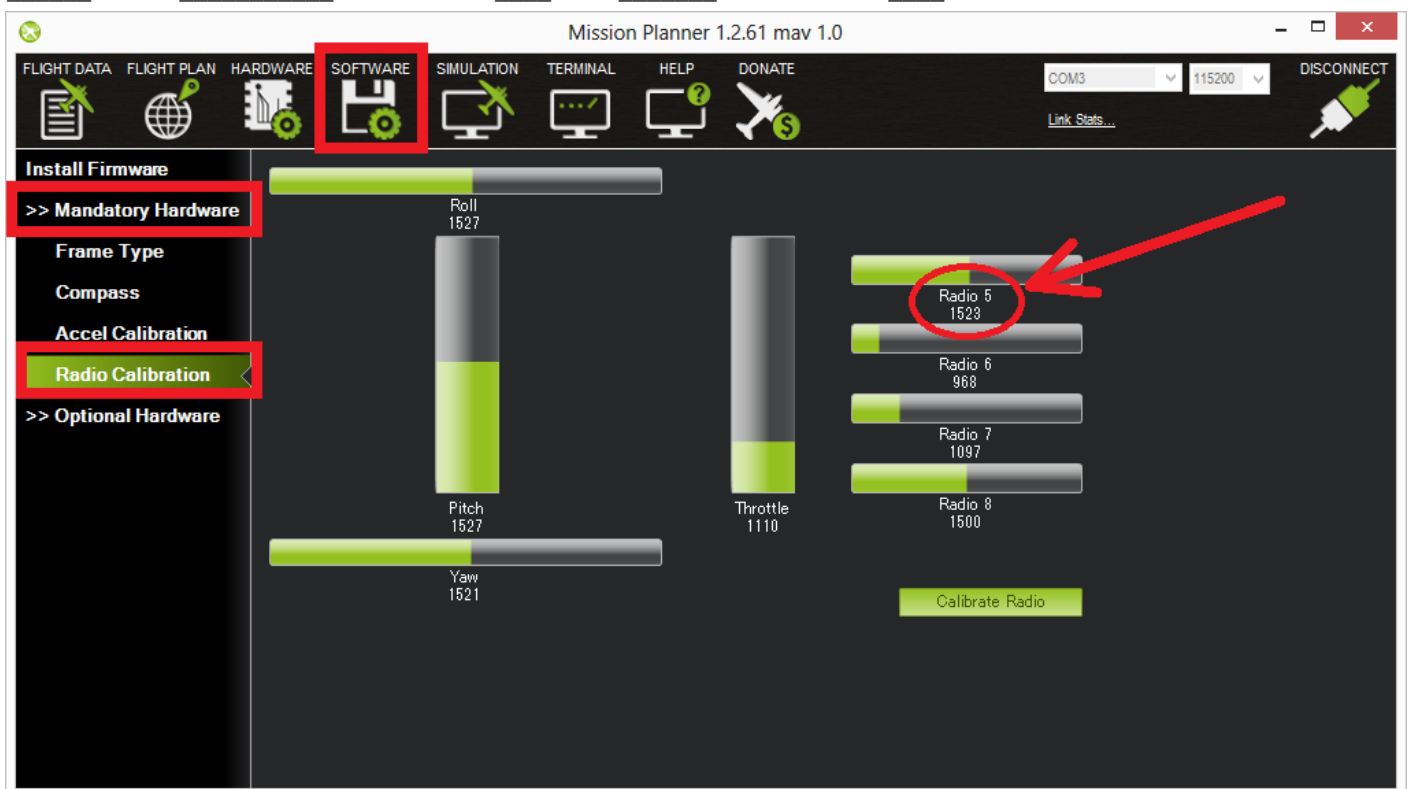
□□□□ 1000□ 2000□□□ (1.0□ 2.0□□□□□)□

$$\mathbb{I} = \mathbb{I}$$

[illegible]

--	--	--	--	--	--	--	--	--

□□□□□□ □□□□□□□□□□ □□□□ □□□□□□□□ PWM□□□□ .

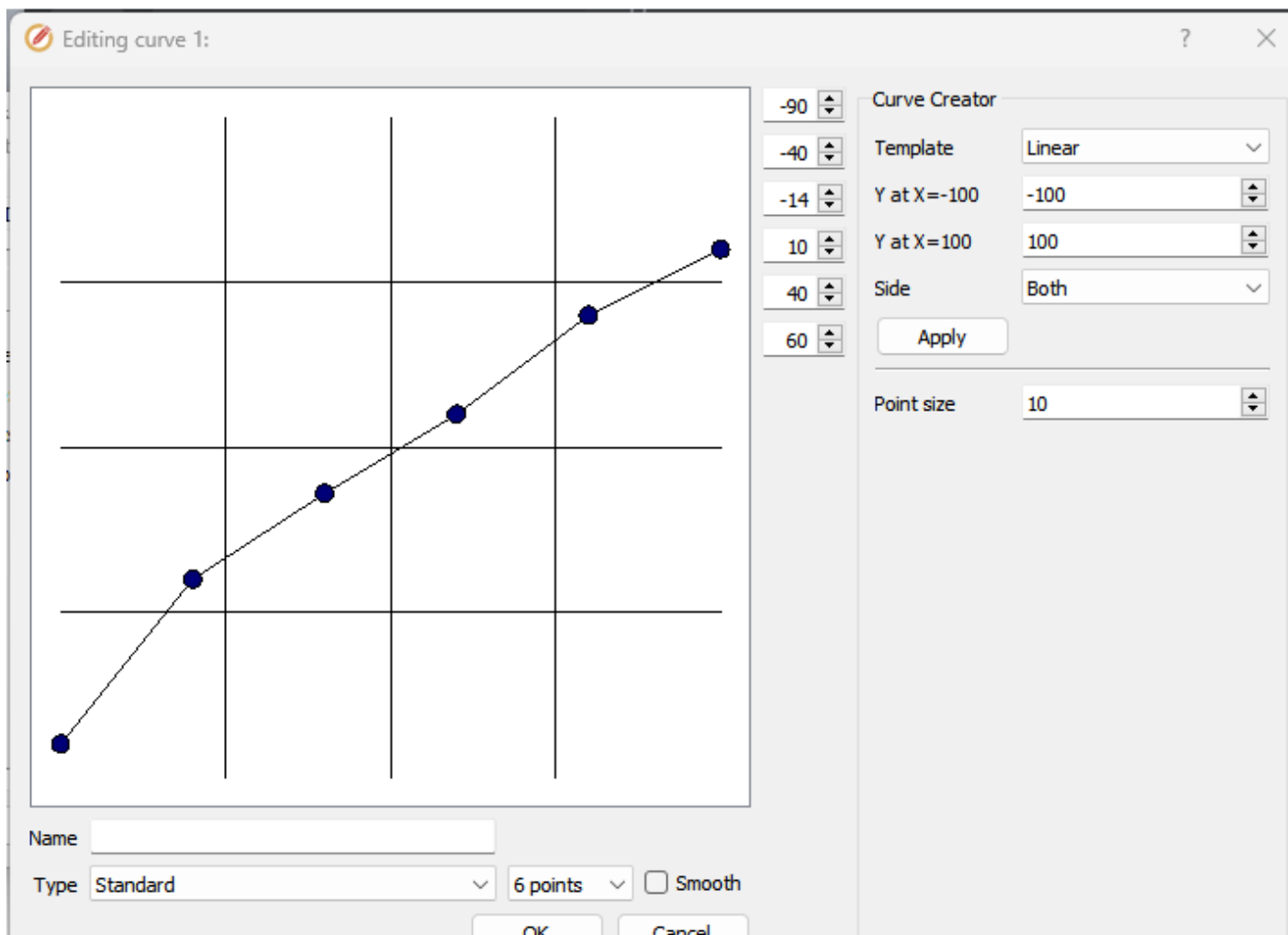


) □ □ :

- ☐ ☐ ☐ ☐ **OpenTX** ☐ ☐ ☐ ☐ :

--	--

6P Weight (+100%) Custom (CV1) [Mode]



- [JR XG8](#)
- [9303](#)
- [JR X2720 \(\)](#).
- [FS-I6](#)
- [T8FG](#)
- [T8J](#)
- [T7CP](#)
- [T6EX](#)
- [Futaba 9ZAP/](#)
- [T10CAG](#)
- [T14](#)
- [T14SG](#)
- [9C](#)
- [MX-16](#)
- [9x\(\)](#) () (!) - [ER9x](#) [Turnigy 9x](#)
- [9XR](#)
- [TGY-I6](#)
- [9](#)
- [Spektrum DX8](#) ()
- [Spektrum DX7](#)
- [Spektrum DX7](#) 6

!

Spektrum DX8()

6 : DX8. Gear ,

. PW

1. (6)
 - , DX8, Switch Select, :
 - Gear = Gear(5)
 - FMODE = Inh - Gear Sw(Channel 5) 6
 - :
 - Knob to aux1 = 6 / .

- ```
[copywiki ='copter,plane,rover,planner,blimp,sub'].
```

