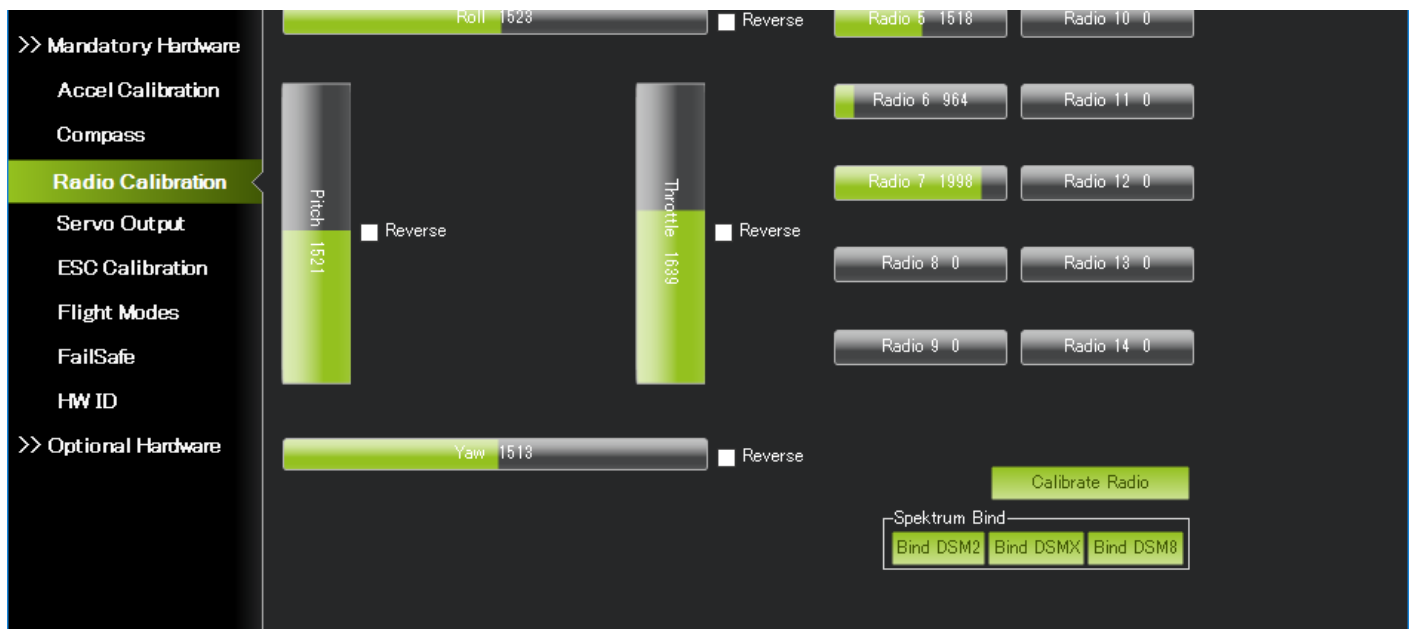


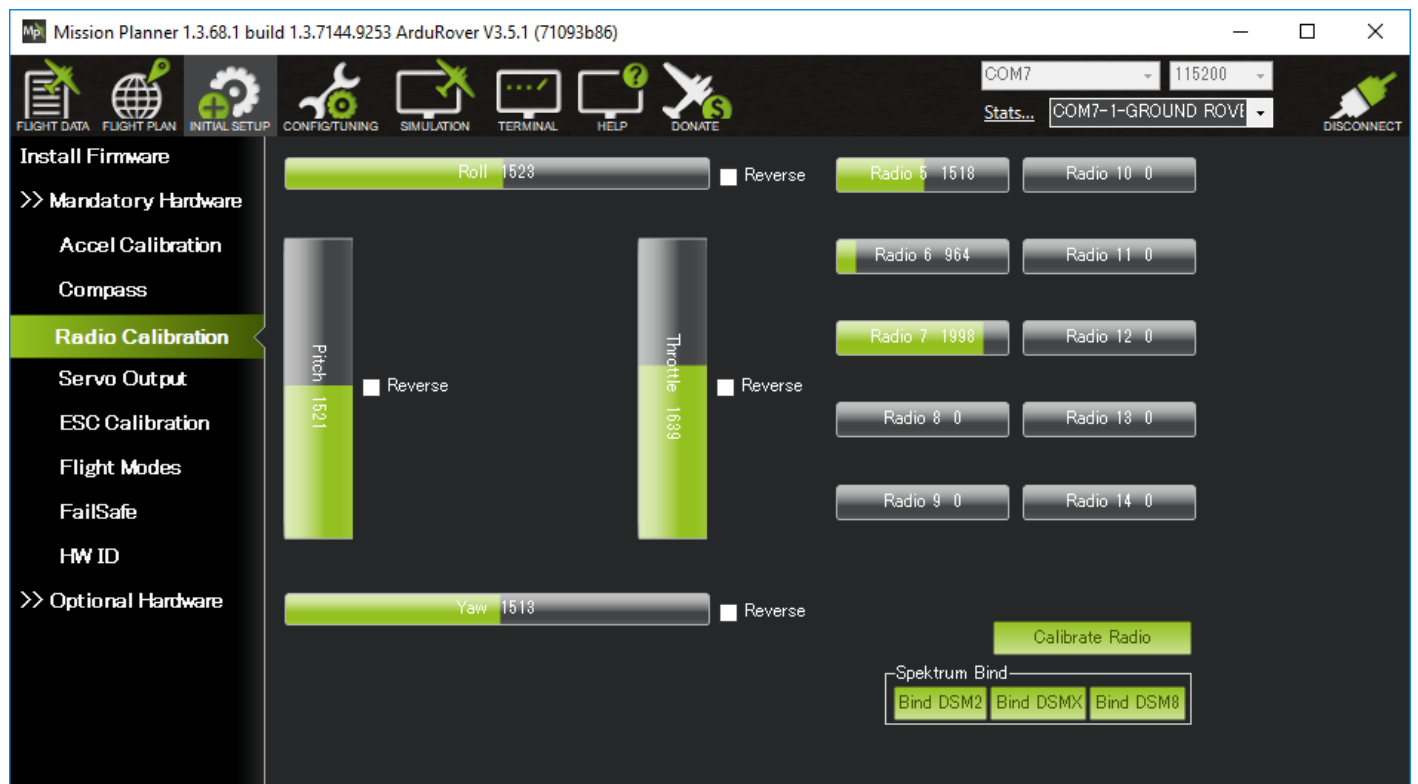
- 
- 
-  LED  ,  RC  /   RC 



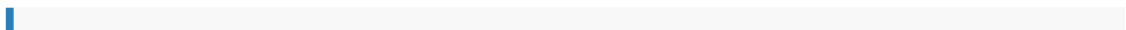
- [illegible]

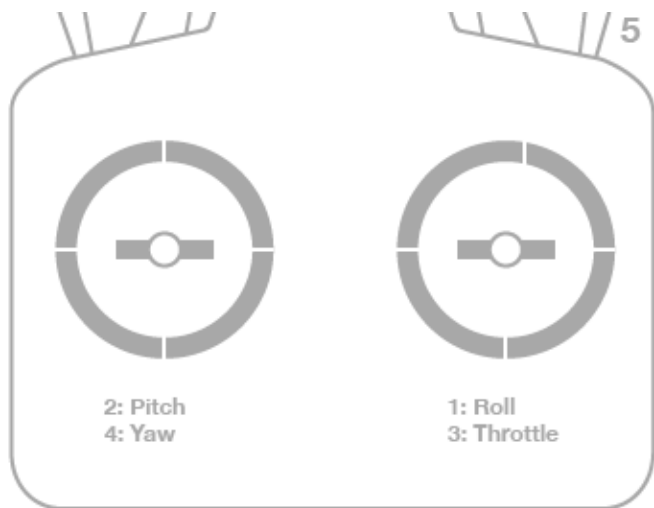
- [] [] [] [] [] [] [] [] , [] [] , [] [] , yaw [] , [] [] [] [] [] [] [] [] :

- o 0000 ,000 yaw00 ,00000000000000000000
- o 0000 ,00000000 00 000000000000

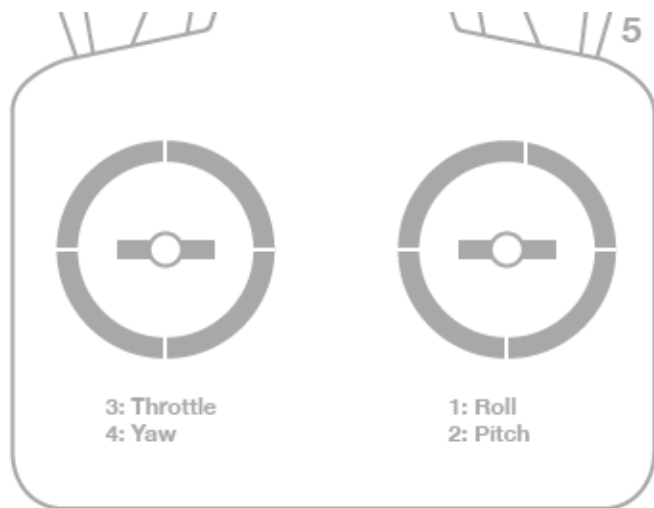


- 00000000 (00000000 2018-09-21) (00 (00)). Inital SETUP → 0000 → 0000 00
- 00000000 “ Calibrate Radio” 00
- 0 “OK”0 ,000000000000 ,000000 ,000000





Mode 1



Mode 2

1. 设置模式：

- 3: 模式 1, 4: 模式 2
- 4: 模式 1; 5: 模式 2

3 2, 4 1, 5 /

[mode = "rover"].



[mode = "copter"]].

1. 设置模式：

- 1: 1
- 2: 2
- 3: 3
- 4: 4: Yaw
- 5: 5: (knob)
- 6: (knob) (knob)
- 7: 12: (knob)

[/]

[mode = " "].

uint8_t :

- 1: 1
- 2: 2
- 3: 3
- 4: Yaw
- 8(): . **FLTMODE CH ** RC

uint8_t . []

[= "rover"].

Rover :

- 1: 1
- 3: 3
- 8(): . ** MODE CH ** RC
- 7 12: ()

Spring Centered Throttle Stick

uint8_t

uint8_t , , , . RC
uint8_t , RC . ,
uint8_t

uint8_t , (FORWARD) 1500uS(50%,) , (+100% ~2000us), (REVERSE) , (-100% ~1000us), .
uint8_t , .

[]

uint8_t

- **RCMAP **
- , **RC **

[= "rover"]. - **Steeting ** []

[wiki] =['copter, plane, rover, planner, blimp'] ().

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- #2
- Admin

2026-10-09 14:35:15 UTC
- Admin

2026-10-10 01:44:43 UTC